

Delay-cost Optimal Coupon Delivery in Mobile Opportunistic Networks

Srinivasan Venkatramanan
Joint work with Prof. Anurag Kumar

Department of ECE, IISc.

January 9, 2014

Mobile Opportunistic Networks (MON)

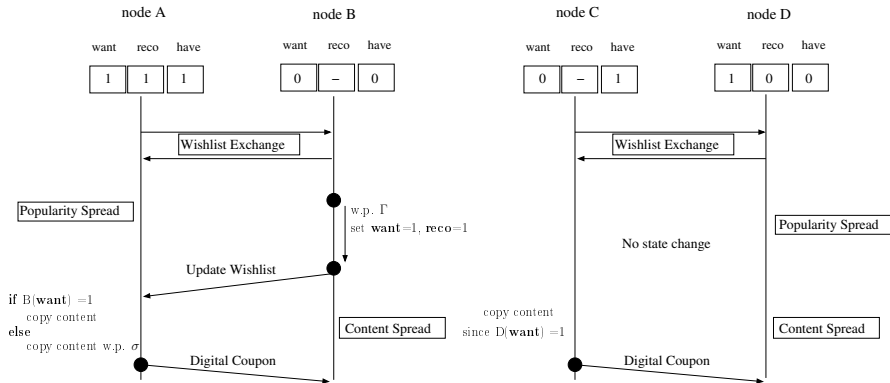
- Proliferation of smart mobile devices
 - Smartphones, tablets, wearable computing devices, etc.
- Mobile content delivery - a challenge
 - Direct delivery - not scalable
 - Alternative: p2p delivery (via Bluetooth, WiFi-Direct, etc.)
- A single item of content may be of **interest** to several co-located users
 - e.g., slides of a conference keynote/ course lecture
- The item can be forwarded between devices when their p2p radio interfaces make contact
 - Akin to **epidemic** spread
 - A multi-hop opportunistic mobile network
 - Provides an approach to *delay tolerant* networking

Mobile Coupon Delivery Ecosystem

- **Scenario:** Pre-release promotions of a product (movie, book, etc.)
- **Content:** discount coupon for pre-ordering the product
- Mobile users can
 - maintain a wishlist of products of interest
 - share wishlists with peers
 - receive coupons from peers or central server
- wishlists + peer recommendation + coupon delivery



A Possible Application Framework

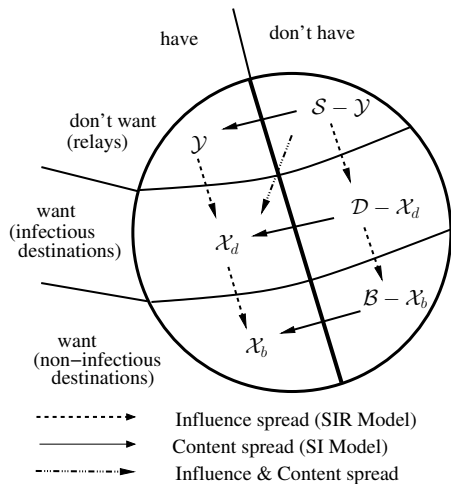


Content Popularity and Dissemination: SIR-SI model

- Population size: N (fixed)
- Pairwise meetings at points of independent Poisson processes
- The coupon needs to reach certain *destination* nodes
- Some destination nodes are given the coupon initially
- The set of destination nodes grows, as more nodes express their interest
- *Do-not-want* nodes could help in forwarding (relays)

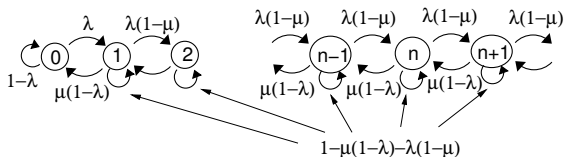
Objective: Quickly spread content to a large fraction of destinations nodes while minimizing the residual number of relays that have the content

SIR-SI States and Evolution

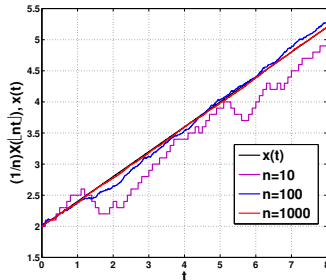
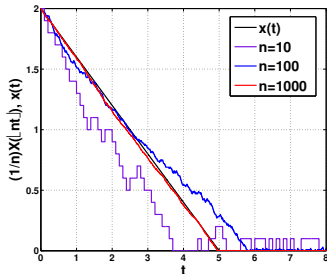


- λ_N : Poisson meeting rate for each pair of nodes; $\lambda_N = \frac{\lambda}{N}$
- β_N : Recovery rate of infectious destinations; $\beta_N = \beta$
- Γ : Influence probability
- σ : Copying probability to a relay (control)

Fluid Limits - Kurtz Theorem



- Queue length process, $X(k), k \geq 0$, $\bar{X}^{(N)}(t) := \frac{1}{N} X(\lfloor Nt \rfloor)$
- ODE: $\dot{x}(t) = (\lambda - \mu) I_{\{x(t) > 0\}}$ with $x(0) = \bar{X}^{(N)}(0)$, for each N



SIR-SI CTMC Markov Chain: Transitions at Meeting Epochs

- Let $k = 0, 1, 2, \dots$ index the meeting/recovery epochs at times t_k
- System state: $Z(k) = (B(k), D(k), X_b(k), X_d(k), Y(k))$

Epoch type	Rate	State update δ_k
$\mathcal{D} - \mathcal{X}_d$ recovers	$\beta_N(D(k) - X_d(k))$	$(1, -1, 0, 0, 0)$
\mathcal{X}_d recovers	$\beta_N X_d(k)$	$(1, -1, 1, -1, 0)$
$\mathcal{B} - \mathcal{X}_b$ meets $\mathcal{X} + \mathcal{Y}$	$\lambda_N(B(k) - X_b(k))(X(k) + Y(k))$	$(0, 0, 1, 0, 0)$
$\mathcal{D} - \mathcal{X}_d$ meets \mathcal{Y}	$\lambda_N(D(k) - X_d(k))Y(k)$	$(0, 0, 0, 1, 0)$ + $(0, 1, 0, 1, -1)$ w.p. Γ
$\mathcal{D} - \mathcal{X}_d$ meets \mathcal{X}	$\lambda_N(D(k) - X_d(k))X(k)$	$(0, 0, 0, 1, 0)$
\mathcal{X}_d meets \mathcal{Y}	$\lambda_N X_d(k)Y(k)$	$(0, 1, 0, 1, -1)$ w.p. Γ
$\mathcal{S} - \mathcal{Y}$ meets $\mathcal{X}_b + \mathcal{Y}$	$\lambda_N(X_b(k) + Y(k))(S(k) - Y(k))$	$(0, 0, 0, 0, 1)$ w.p. σ
$\mathcal{S} - \mathcal{Y}$ meets $\mathcal{D} - \mathcal{X}_d$	$\lambda_N(D(k) - X_d(k))(S(k) - Y(k))$	$(0, 1, 0, 0, 0)$ w.p. Γ
$\mathcal{S} - \mathcal{Y}$ meets \mathcal{X}_d	$\lambda_N(X_d(k))(S(k) - Y(k))$	$(0, 1, 0, 1, 0)$ w.p. Γ $(0, 0, 0, 0, 1)$ w.p. $(1 - \Gamma)\sigma$

$$\dot{b} = \beta d$$

$$\dot{d} = -\beta d + \lambda \Gamma ds$$

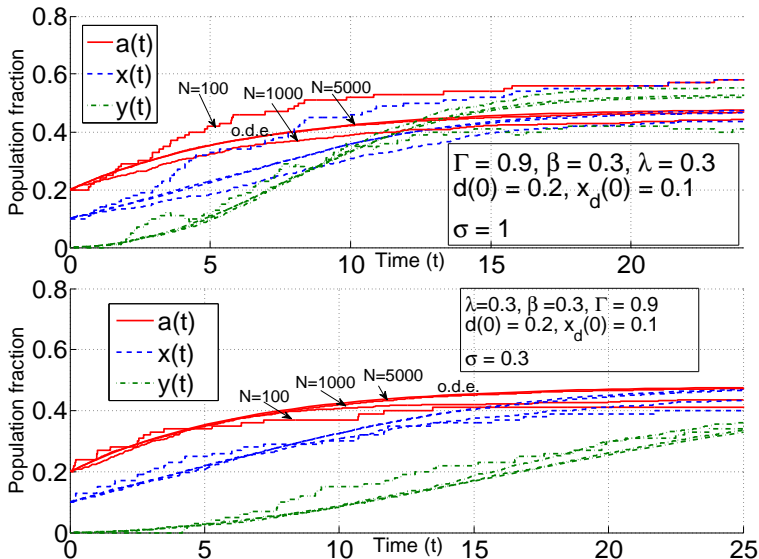
$$\dot{x}_b = \beta x_d + \lambda(b - x_b)(x + y)$$

$$\dot{x}_d = \lambda(d - x_d)(x + y) + \lambda \Gamma dy + \Gamma \lambda x_d(s - y) - \beta x_d$$

$$\dot{y} = -\Gamma \lambda dy + \lambda \sigma(s - y)(x_b + y + (1 - \Gamma)x_d)$$

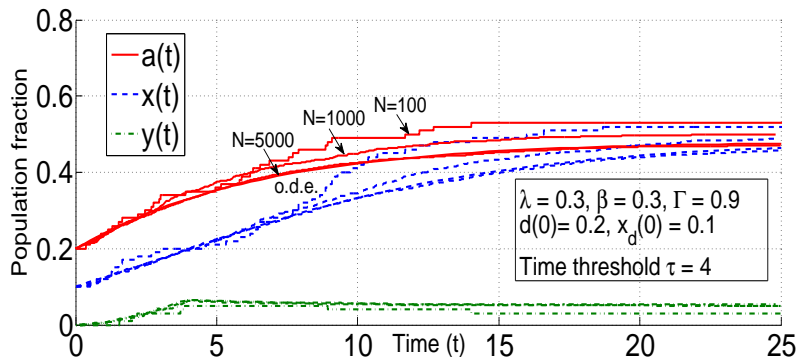
where $s(t) = 1 - b(t) - d(t)$

Convergence of the CTMC to O.D.E. Limit



SIR-SI Model: Dynamic Control of Copying

- Dynamic control $\sigma : Z(k) \rightarrow [0, 1]$
- CTMDP for each N : Obtaining optimal control is difficult
- Replace probabilistic control σ in the ODE by $\sigma(t)$ (controlled ODE)
- Optimal (deterministic, open-loop) control for the controlled ODE
- Can be shown to be asymptotically optimal for the finite size problem



Optimal Control

Target time: $T_\sigma = \inf\{t : x_\sigma(t) \geq \alpha a(\infty)\}$

- $a(\infty) = b(\infty) + d(\infty)$: terminal fraction of destinations
- $x_\sigma(t)$: fraction of destinations that have the coupon at time t

Cost function: $C_\sigma = \psi y_\sigma(T_\sigma) + T_\sigma = \psi y_\sigma(T_\sigma) + \int_0^{T_\sigma} 1 dt$

- $y_\sigma(T_\sigma)$: fraction of relays that have the coupon at time T_σ

Theorem

For the above o.d.e. system, for the cost function displayed earlier, there exists an optimal control of the form,

$$\sigma_\tau(t) = \begin{cases} 1, & 0 < t < \tau \\ 0, & t \geq \tau \end{cases}$$

- Distributed implementation: Time stamping of the coupon

Optimality of a Time Threshold Control: Sketch of Proof

- Define Kamke dominance: extension of Kamke condition for o.d.e.s
- Here Kamke dominance holds, hence $\forall t, \sigma^{(1)}(t) \geq \sigma^{(2)}(t)$, and

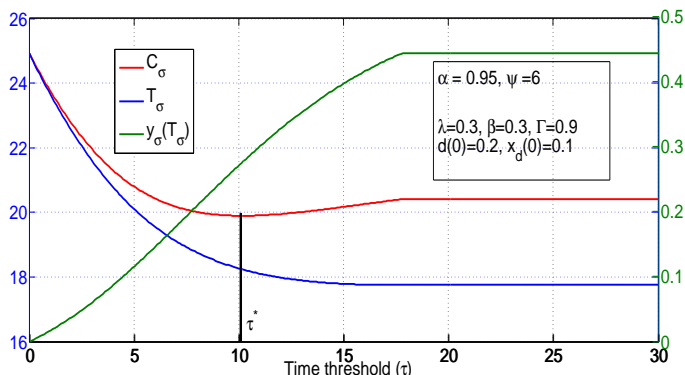
$$(x_b^{(1)}(0), x_d^{(1)}(0), y^{(1)}(0)) \geq (x_b^{(2)}(0), x_d^{(2)}(0), y^{(2)}(0)),$$

implies that, $\forall t$,

$$(x_b^{(1)}(t), x_d^{(1)}(t), y^{(1)}(t)) \geq (x_b^{(2)}(t), x_d^{(2)}(t), y^{(2)}(t))$$

- Consider $\sigma(t)$ (any action function) and $\sigma_\tau(t)$ (a time threshold action function) such that $y_\sigma(T_\sigma) = y_{\sigma_\tau}(T_{\sigma_\tau}) = \rho$
 - We can show that $T_{\sigma_\tau} \leq T_\sigma$ and hence the time threshold action function is optimal in $\{\sigma(\cdot) : y_\sigma(T_\sigma) = \rho\}$
- Define $\rho_{max} = \max\{y_{\sigma_\tau}(T_{\sigma_\tau}) : \tau \geq 0\}$
 - Consider an action function $\sigma(t)$ with $y_\sigma(T_\sigma) > \rho_{max}$
 - The threshold policy with $\tau := \sup\{t : \sigma(t) > 0\}$ has lower cost

Optimal Control for the Running Example



- $\alpha = 0.95, C_\sigma = 6y_\sigma(T_\sigma) + T_\sigma$
- The optimal control is to copy until $\tau = 10.1$ and then stop copying

Conclusion and Future Work

- A possible application framework for coupon delivery
- Delay-cost optimal forwarding
 - Joint evolution of content delivery and popularity
 - Modeled as CTMC and obtained the fluid limits
- Existence of Time-threshold control which is delay-cost optimal
- Performance of optimal fluid policy for the finite N case
- **Possible extensions:**
 - Multiple items of content; communities of interest
 - Large content: divided into several chunks
 - Service pricing, and incentive mechanisms for relays

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